

APPENDIX TO PAPER 5

THE MATHEMATICAL RELATIONSHIP BETWEEN EUCLIDEAN SPACE AND RAPIDITY SPACE.

(Paper 5: *Velocity addition formula from euclidean space analogue*,
www.euclideanrelativity.net , S. Kanagaraj, 20 Dec 2009).

- The relationships between velocity v , rapidity α , Lorentz ratio γ , proper velocity V , orientation angle ϕ and spacetime angle θ are shown below.

1. Table 1: The relationships between $v, \alpha, \gamma, V, \phi$ and θ .

	$f(v)$	$f(\alpha)$	$f(\gamma)$	$f(V)$	$f(\phi)$	$f(\theta)$
Velocity, v	v	$\tanh \alpha$	$\frac{\sqrt{\gamma^2 - 1}}{\gamma}$	$\frac{V}{\sqrt{1 + V^2}}$	$\sin \phi$	$\cos \theta$
Rapidity, α	$\operatorname{arctanh} v$	α	$\frac{\operatorname{arctanh} \frac{\sqrt{\gamma^2 - 1}}{\gamma}}{\gamma}$	$\operatorname{arcsinh} V$	$\operatorname{arctanh}(\sin \phi)$	$\operatorname{arctanh}(\cos \theta)$
Lorentz ratio, γ	$\frac{1}{\sqrt{1 - v^2}}$	$\cosh \alpha$	γ	$\sqrt{1 + V^2}$	$\sec \phi$	$\operatorname{cosec} \theta$
Proper velocity, V	$\frac{v}{\sqrt{1 - v^2}}$	$\sinh \alpha$	$\sqrt{\gamma^2 - 1}$	V	$\tan \phi$	$\cot \theta$
Orientation angle, ϕ	$\operatorname{arcsin} v$	$\operatorname{arcsin}(\tanh \alpha)$	$\operatorname{arcsec} \gamma$	$\operatorname{arctan} V$	ϕ	$\operatorname{arcsin}(\cos \theta)$
Spacetime angle, θ	$\operatorname{arccos} v$	$\operatorname{arccos}(\tanh \alpha)$	$\operatorname{arccosec} \gamma$	$\operatorname{arccot} V$	$\operatorname{arccos}(\sin \phi)$	θ

Note: The relationship between v, α and γ are familiar while the variables V, ϕ and θ are introduced in euclidean interpretation of relativity.

2. The differential relationship between v , α , γ , V , ϕ and θ .

(i) From $v = \tanh \alpha$, $\frac{dv}{d\alpha} = \operatorname{sech}^2 \alpha$ and $\frac{d\alpha}{dv} = \cosh^2 \alpha$

From Table 1, $\cosh \alpha = \sec \phi = \operatorname{cosec} \theta = \frac{1}{\sqrt{1-v^2}} = \gamma = \sqrt{1+V^2}$

Thus $\frac{d\alpha}{dv} = \sec^2 \phi = \operatorname{cosec}^2 \theta = \cosh^2 \alpha = \frac{1}{1-v^2} = \gamma^2 = (1+V^2)$

(ii) From $v = \sin \phi$, $\frac{dv}{d\phi} = \cos \phi$ and $\frac{d\phi}{dv} = \sec \phi$

From $v = \cos \theta$, $\frac{dv}{d\theta} = -\sin \theta$ and $\frac{d\theta}{dv} = -\operatorname{cosec} \theta$

Thus $\frac{d\phi}{dv} = \sec \phi = -\frac{d\theta}{dv} = \operatorname{cosec} \theta = \cosh \alpha = \frac{1}{\sqrt{1-v^2}} = \gamma = \sqrt{1+V^2}$

(iii) From $V = \frac{v}{\sqrt{1-v^2}} = v(1-v^2)^{-1/2}$

$$\frac{dV}{dv} = v \left\{ \left[-\frac{1}{2} (1-v^2)^{-3/2} \right] (-2v) \right\} + (1-v^2)^{-1/2}$$

$$= \frac{v^2}{(1-v^2)\sqrt{1-v^2}} + \frac{1}{\sqrt{1-v^2}}$$

$$= \frac{v^2 + (1-v^2)}{(1-v^2)\sqrt{1-v^2}}$$

$$= \left(\frac{1}{\sqrt{1-v^2}} \right)^3$$

$$= \gamma^3$$

Thus $\frac{dV}{dv} = \gamma^3 = \sec^3 \phi = \operatorname{cosec}^3 \theta = \cosh^3 \alpha$

$$\begin{aligned}
 \text{(iv)} \quad \frac{d\phi}{dV} &= \frac{d\phi}{dv} \times \frac{dv}{dV} \\
 &= \gamma \times \frac{1}{\gamma^3} \\
 &= 1/\gamma^2
 \end{aligned}$$

$$\text{Thus } \frac{dV}{d\phi} = \gamma^2 = \sec^2 \phi = -\frac{dV}{d\theta} = \operatorname{cosec}^2 \theta = \cosh^2 \alpha = \frac{1}{1-v^2} = 1+V^2 = \frac{d\alpha}{dv}$$

$$\begin{aligned}
 \text{(v)} \quad \frac{dV}{d\alpha} &= \frac{dV}{dv} \times \frac{dv}{d\alpha} \\
 &= \gamma^3 \times \frac{1}{\gamma^2} \\
 &= \gamma
 \end{aligned}$$

$$\text{Thus } \frac{dV}{d\alpha} = \gamma = \sec \phi = \frac{1}{\sqrt{1-v^2}} = \cosh \alpha = \sqrt{1+V^2} = \frac{d\phi}{dv} = -\frac{d\theta}{dv} = \operatorname{cosec} \theta$$

$$\begin{aligned}
 \text{(vi)} \quad \frac{d\alpha}{d\phi} &= \frac{d\alpha}{dv} \times \frac{dv}{d\phi} \\
 &= \gamma^2 \times \frac{1}{\gamma} \\
 &= \gamma
 \end{aligned}$$

Summary of the differential relationship

$$-\frac{d\theta}{dv} = \frac{d\phi}{dv} = \frac{dV}{d\alpha} = \frac{d\alpha}{d\phi} = \gamma$$

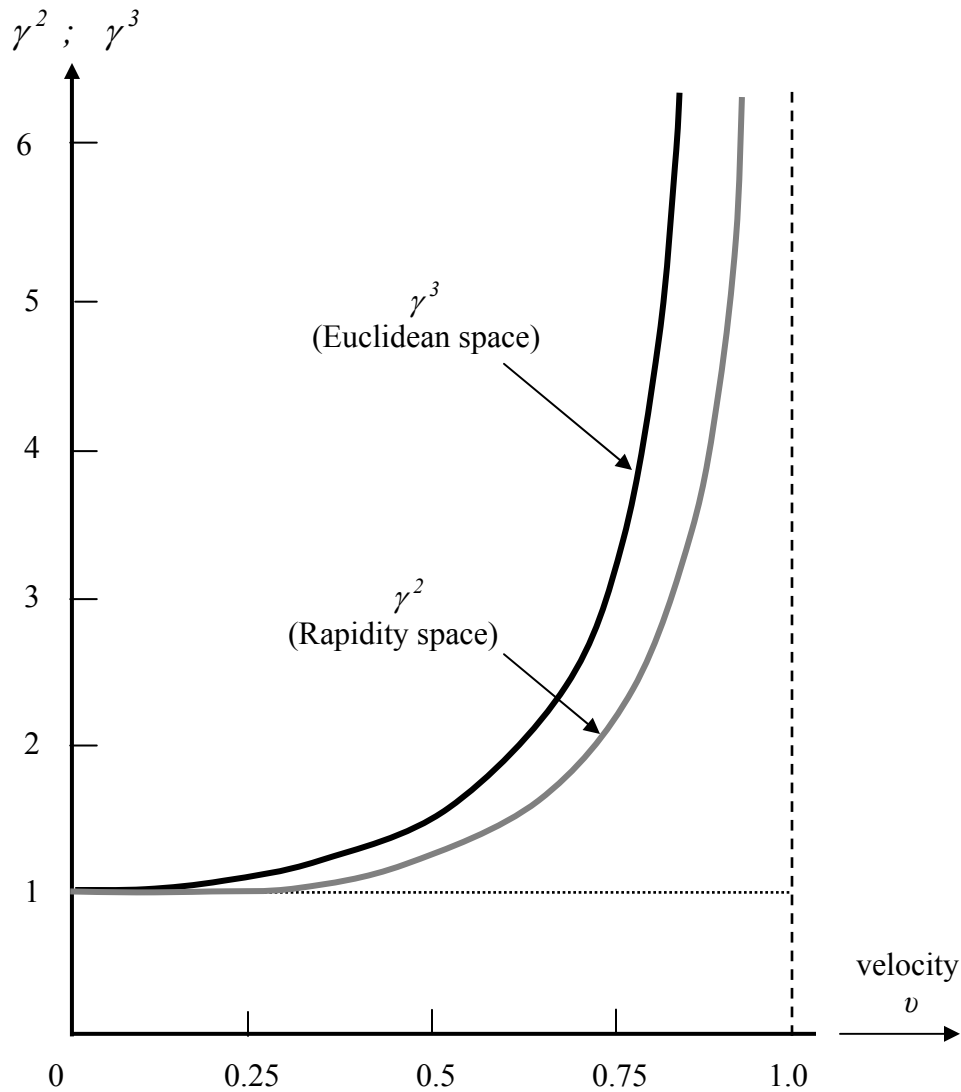
$$-\frac{dV}{d\theta} = \frac{d\alpha}{dv} = \frac{dV}{d\phi} = \gamma^2$$

$$\frac{dV}{dv} = \gamma^3$$

3. Investigating the addition of rapidity α and proper velocity V from the integral functions of rapidity space and euclidean space.

In rapidity space, $\frac{d\alpha}{dv} = \gamma^2$, where $\gamma = \frac{1}{\sqrt{1-v^2}}$. Thus $\alpha = \int \gamma^2 dv$. This translates as rapidity α

is the area under the graph of γ^2 vs v . In euclidean space, $\frac{dV}{dv} = \gamma^3$, thus $V = \int \gamma^3 dv$. This translates as the proper velocity V , is the area under the graph of γ^3 vs v .



Graph of γ^2 vs v and γ^3 vs v for range of $0 < v < 1$

For the velocity v range $0 < v < 1$, both the graphs γ^2 & γ^3 ranges from 1 to ∞ and at low velocities both remains close to 1, showing $v \approx \alpha \approx V$ when $v \ll 1$. Since $\gamma^3 > \gamma^2$, for the same area under the graphs representing the proper velocity V and rapidity α , the velocity v from euclidean space is slightly less than its corresponding value in rapidity space. (This is consistent with Fig 2 graph in paper 5).

Noting that $\gamma = \sec \phi$ and $dv = \cos \phi d\phi$ (from 2i & 2ii above), the integral function of rapidity α and proper velocity V can be expressed in terms of ϕ instead of v .

$$\begin{aligned} \text{From } \alpha &= \int_0^v \gamma^2 dv, \text{ substituting } \gamma \text{ and } dv, \\ &= \int_0^\phi \sec^2 \phi \cos \phi d\phi \\ &= \int_0^\phi \sec \phi d\phi \\ &= \ln(\sec \phi + \tan \phi) \end{aligned}$$

Thus $e^\alpha = \sec \phi + \tan \phi$. From this, $e^\alpha = \frac{1 + \sin \phi}{\cos \phi}$ and $e^{-\alpha} = \frac{\cos \phi}{1 + \sin \phi}$. Substituting into

$\frac{e^\alpha - e^{-\alpha}}{e^\alpha + e^{-\alpha}}$, the relationship simplifies as $\tanh \alpha = \sin \phi$, consistent with as in Table 1.

$$\begin{aligned} \text{From } V &= \int_0^v \gamma^3 dv \\ &= \int_0^\phi \sec^3 \phi \cos \phi d\phi \\ &= \int_0^\phi \sec^2 \phi d\phi \\ &= \tan \phi \end{aligned}$$

This is consistent with $V = \tan \phi$ as in Table 1.

Since $\sec \phi = \gamma$, for the graph γ vs ϕ (rapidity space) and γ^2 vs ϕ (euclidean space), the ϕ range is $0 < \phi < \frac{\pi}{2}$ corresponding with v range $0 < v < 1$. Alternatively expressed as a $f(\theta)$, the resulting equations are consistent with the above.

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